

OKLAHOMA STATE UNIVERSITY  
SCHOOL OF ELECTRICAL AND COMPUTER ENGINEERING



ECEN 5713 Linear Systems  
Spring 2001  
Final Exam



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**choose four out of five problems: please indicate as below.**

**1).** \_\_\_\_\_ **2).** \_\_\_\_\_ **3).** \_\_\_\_\_ **4).** \_\_\_\_\_

**Problem 1:**

Find the *observable* canonical form realization (in minimal order) from SISO continuous-time system given below:

$$\frac{d^4 y(t)}{dt^4} + 3t \frac{d^3 y(t)}{dt^3} + 4 \frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + \alpha(t)y(t) = \frac{d^2 u(t)}{dt^2} + e^{-t} \frac{du(t)}{dt} + u(t).$$

Notice that gain blocks may be *time* dependent. Show the state space representation and its corresponding simulation diagram.

**Problem 2:**

There exists a similarity transformation matrix  $P$  such that

$$PAP^{-1} = A_c = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \\ -\alpha_0 & -\alpha_1 & -\alpha_2 & \cdots & -\alpha_{n-1} \end{bmatrix}.$$

Show that if  $\lambda$  is an eigenvalue of the companion matrix  $A_c$ , then a corresponding eigenvector is

$$v = \begin{bmatrix} 1 & \lambda & \cdots & \lambda^{n-1} \end{bmatrix}^T.$$

**Problem 3:**

For the matrices

$$A_1 = \begin{bmatrix} 2 & 2 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \text{ and } A_2 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix},$$

determine the functions of matrices  $e^{A_1 t}$ ,  $A_2^{99}$ ,  $\cos A_2 t$ .

**Problem 4:**

Show that the two linear systems

$$\dot{x}^{(1)}(t) = \begin{bmatrix} 0 & 1 \\ 2-t^2 & 2t \end{bmatrix} x^{(1)}(t) = A_1(t)x^{(1)}(t)$$

and

$$\dot{x}^{(2)}(t) = \begin{bmatrix} t & 1 \\ 1 & t \end{bmatrix} x^{(2)}(t) = A_2(t)x^{(2)}(t)$$

are equivalent state-space representations of the differential equation

$$\ddot{y}(t) - 2t\dot{y}(t) - (2-t^2)y(t) = 0.$$

- a) For which choice is it easier to compute the state transition matrix  $\Phi(t, t_0)$ ? For this case, compute  $\Phi(t, 0)$ .
- b) Determine the relation between  $x^{(1)}(t)$  and  $y(t)$  and between  $x^{(2)}(t)$  and  $y(t)$ .

**Problem 5:**

Consider the equivalent dynamical equations

$$\dot{x} = Ax + Bu$$

$$y = Cx$$

and

$$\dot{\bar{x}} = \bar{A}\bar{x} + \bar{B}u$$

$$y = \bar{C}\bar{x}$$

where  $\bar{x} = Px$ . Their adjoint equations are, respectively,

$$\dot{z} = -A^*z + C^*u \quad (1)$$

$$y = B^*z$$

and

$$\dot{\bar{z}} = -\bar{A}^*\bar{z} + \bar{C}^*u \quad (2)$$

$$y = \bar{B}^*\bar{z}$$

where  $A^*$  and  $\bar{A}^*$  are the complex conjugate transposes of  $A$  and  $\bar{A}$ , respectively. Show that Equations (1) and (2) are equivalent and they are related by  $\bar{z} = (P^{-1})^* z$ .